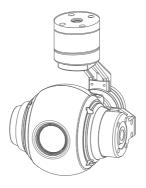


Quick Start Guide

Q10F

10x Optical Zoom Camera Gimbal

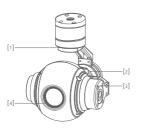


Images are for reference only, please subject to the actual product.

Q10F

The Q10F gimbal and camera features an 10x optical zoom lens. The type 1/3 inch CMOS sensor supports approx, 4 million effective pixels, HD 1080p video, fast auto-focus speed ,small size,designed for UAV aerial photography. Factory, all the parameters have been perfectly set, you just need to install the gimbal camera to UAV ,then Ready to fly. The gimbal can be controlled in three directions: YAW, ROLL and PITCH, we use FOC solution can greatly compensate the vibration of UAV. The image is very stable even at ten optical zoom times. Q10F have been widely used in various fields like public security, electric power, fire, zoom aerial photography and other industries in the application of drones.

Q10F Overview



- [1] YAW axis motor
- [2] Roll axis motor
- [3] Pitch axis motor
- [4] 10x HD zoom camer



Please make sure that the motor is not stopped by any object during the rotation, if the gimbal is blocked during rotation, please remove the obstruction immediately.

In the Box

Gimbal camera*1

Button head hexagon screw*8







5mm*4

8mm*4

Copper cylinders*4

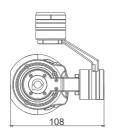
Anti shedding buckle*4

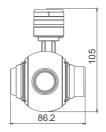




Gimbal Camera Dimension

Uint: mm





Installing

Install the holder camera as shown



Connection of Control Box and Wiring Instruction



Control Box position



1.Insert SD card

SD card: max 32G ,class10 FAT32 or exFAT format

2.Connect HDMI to display

HDMI : micro HDMI OUTPUT 1080P 60fps default

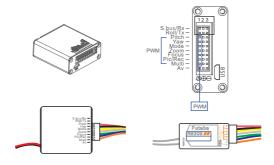


SD card position

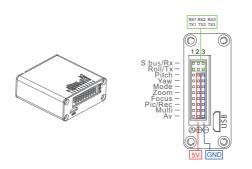


HDMI position

3. Connect the signal line as below

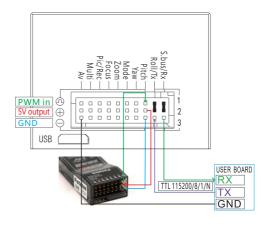


4. Power supply with 12V, red line is positive and black is negative.



Function Description

Signal functions

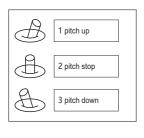


S.bus/Rx: connect to Rx2 for track function.

Roll/ Tx: connect to Tx2 for track function.

Pitch: PWM in, pitch control

Pitch: PWM in, pitch control



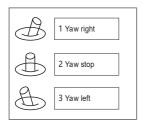
We have protocol for control the gimbal and camera, please contact our technical support for detail doc.

USER BOARD / GPS module RX

TX

GND

Yaw: PWM in, Yaw control



Mode: Change the speed / home position



Position 1: Lowest speed for pitch and yaw.

Position 2: Middle speed for pitch and yaw.

Position 3: Highest speed for pitch and yaw. The speed is continuously quickly from 1 to 3

One click: Home position.

Two click: Look down.

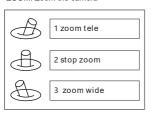
Three click: Yaw not followed by frame.

Four click: Yaw followed by frame.

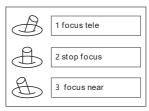
Five click: Restore the factory settings.

(Click = from 2 to 3 and back to 2 quickly)

ZOOM: Zoom the camera



Focus: Focus the camera



Pic/ Rec picture / Start record, stop record



Multi: backup PWM channel for customize



AV: AV output .

| Heat an Brownite | | |
|---------------------------|---|--|
| Working voltage 12V ~ 16V | | |
| | 3S ~ 4S | |
| Input voltage | | |
| Output voltage | 5V (connect with PWM) | |
| Dynamic current | 320mA @ 12V | |
| Idle current | 240mA @ 12V | |
| Power consumption | ≤ 3.85W | |
| Working environment temp. | -20℃ ~ +50℃ | |
| Output | micro HDMI(HD output 1080P 60fps) / Analog | |
| Local-storage | SD card (Up to 32G, class 10, FAT32 or ex FAT format) | |
| Control method | PWM / TTL | |
| | Gimbal Spec | |
| Pitch/Tilt | ±90° | |
| Roll | ±45° | |
| Yaw/Pan | ±150° | |
| Vibration angle | Pitch/Roll: ±0.02°, Yaw: ±0.03° | |
| One-key to center | √ | |
| | Camera Spec | |
| Imager Sensor | 1/3inch CMOS | |
| Total pixel | 4MP | |
| Effective pixel | 2688*1520 | |
| Dynamic range | 65dB | |
| Lens | 5MP | |
| Optical zoom | 10x, F=4.9~49mm | |
| Min object distance | 1.5M | |
| Viewing angle | Horizontal: 53.2°(Wide end) ~ 5.65°(Tele end) | |
| | Vertical: 39.8°(wide end) ~ 4.2°(tele end) | |
| | Focus: 66.6°(wide end) ~ 7.2°(tele end) | |
| Sync system | Progressive scanning | |
| Local video | 1080P 30fps local TF card | |
| HD output | 1080P/720/480P 60fps HDMI1.4 | |
| AV output | Standard CVBS 1Vp-p | |

| S/N ratio | 38dB |
|------------------------------------|--|
| Min illumination | Color 0.05lux@F1.6 |
| Backlight compensation | Backlight compensation/strong light inhibition |
| Gain | Auto |
| White balance | Auto/Manual |
| Shutter speed | Auto |
| Control system | UART/IR/PWM |
| Communication protocol | PELCO-D, Hitachi protocol or VISCA |
| Focus | Auto/Manual/One-time automatic focus |
| Focus speed | 2s |
| Lens initialization | Built-in |
| User presetting bit | 20 sets |
| Image rotation | 180°, Horizontal/Vertical mirror image |
| OSD | Not support |
| Fotoformate | JPEG |
| Videoformate | MP4 |
| Fotoformate | JPEG |
| Videoformate | MP4 |
| Came | era Object Tracking(Optional) |
| Update rate of deviation pixel | 50Hz |
| Output delay of deviation pixel | <15ms |
| Minimum object contrast | 5% |
| SNR | 4 |
| Minimum object size | 16*16 pixel |
| Maximum object size | 160*160 pixel |
| Tracking speed | ±32 pixel/frame |
| Object memory time | 4s |
| The mean square root values of | < 0.5 pixel |
| pulse noise in the object position | Packing Information |
| N W | 413g |
| Product meas | 105°91°98mm |
| Accessories | 1pc gimbal camera device, 16pcs screws / Hight quality |
| 7000 3001103 | plastic box with foam cushion |